## 40MHz, Fast Settling, Unity Gain Stable, Operational Amplifier

The HA-2541 is the first unity gain stable monolithic operational amplifier to achieve 40MHz unity gain bandwidth. A major addition to the Intersil series of high speed, wideband op amps, the HA-2541 is designed for video and pulse applications requiring stable amplifier response at low closed loop gains.

The uniqueness of the HA-2541 is that its slew rate and bandwidth characteristics are specified at unity gain. Historically, high slew rate, wide bandwidth and unity gain stability have been incompatible features for a monolithic operational amplifier. But features such as $250 \mathrm{~V} / \mu$ s slew rate and 40 MHz unity gain bandwidth clearly show that this is not the case for the HA-2541. These features, along with 90ns settling time to $0.1 \%$, make this product an excellent choice for high speed data acquisition systems.

MIL-STD-883 product and data sheets are available upon request.

For further application suggestions on the HA-2541, please refer to Application Note AN550 (Using the HA-2541), and Application Note AN556 (Thermal Safe Operating Areas for High Current Operational Amplifiers). Also see 'Applications' in this data sheet.

For a lower power version of this product, please see the HA-2841 data sheet.

## Features

- Unity Gain Bandwidth. . . . . . . . . . . . . . . . . . . . . . . 40MHz
- High Slew Rate . . . . . . . . . . . . . . . . . . . . . . . . . 250V/ $\mu \mathrm{s}$
- Low Offset Voltage. . . . . . . . . . . . . . . . . . . . . . . . . . 0.8mV
- Fast Settling Time (0.1\%). . . . . . . . . . . . . . . . . . . . . 90ns
- Power Bandwidth . . . . . . . . . . . . . . . . . . . . . . . . . . . 4MHz
- Output Voltage Swing (Min) . . . . . . . . . . . . . . . . . . . $\pm 10 \mathrm{~V}$
- Unity Gain Stability
- Monolithic Bipolar Dielectric Isolation Construction


## Applications

- Pulse and Video Amplifiers
- Wideband Amplifiers
- High Speed Sample-Hold Circuits
- Fast, Precise D/A Converters
- High Speed A/D Input Buffer

Part Number Information

| PART <br> NUMBER | TEMP. <br> RANGE $\left({ }^{\circ} \mathrm{C}\right)$ | PACKAGE | PKG. NO. |
| :---: | :---: | :---: | :--- |
| HA1-2541-5 | 0 to 75 | 14 Ld CERDIP | F14.3 |

## Pinout

HA1-2541
(CERDIP)
TOP VIEW


| Absolute Maximum Ratings |  |
| :---: | :---: |
| Voltage Between V+ and V- Terminals | 35V |
| Differential Input Voltage | 6 V |
| Peak Output Current | 50 mA |
| Continuous Output Current | $28 \mathrm{~mA} \mathrm{RMS}^{\text {a }}$ |

## Operating Conditions

Temperature Range
HA-2541-5 . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $0^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$
CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTES:

1. Maximum power dissipation with load conditions must be designed to maintain the maximum junction temperature below $175^{\circ} \mathrm{C}$. By using Ap plication Note AN556 on Safe Operating Area equations, along with the thermal resistances, proper load conditions can be determined. Heat sinking is recommended above $75^{\circ} \mathrm{C}$.
2. $\theta_{J A}$ is measured with the component mounted on an evaluation PC board in free air

## Electrical Specifications $\quad V_{S U P P L Y}= \pm 15 \mathrm{~V}, R_{L}=1 \mathrm{k} \Omega, C_{L} \leq 10 \mathrm{pF}$, Unless Otherwise Specified

| PARAMETER | TEST CONDITIONS | TEMP $\left({ }^{\circ} \mathrm{C}\right)$ | $\begin{gathered} \text { HA-2541-5 } \\ 0^{\circ} \mathrm{C} \text { TO } 75^{\circ} \mathrm{C} \end{gathered}$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX |  |
| INPUT CHARACTERISTICS |  |  |  |  |  |  |
| Offset Voltage |  | 25 | - | 1 | 2 | mV |
|  |  | Full | - | - | 6 | mV |
| Average Offset Voltage Drift |  | Full | - | 9 | - | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| Bias Current |  | 25 | - | 11 | 35 | $\mu \mathrm{A}$ |
|  |  | Full | - | - | 50 | $\mu \mathrm{A}$ |
| Average Bias Current Drift |  | Full | - | 85 | - | $n A /{ }^{\circ} \mathrm{C}$ |
| Offset Current |  | 25 | - | 1 | 7 | $\mu \mathrm{A}$ |
|  |  | Full | - | - | 9 | $\mu \mathrm{A}$ |
| Input Resistance |  | 25 | - | 100 | - | $\mathrm{k} \Omega$ |
| Input Capacitance |  | 25 | - | 1 | - | pF |
| Common Mode Range |  | Full | $\pm 10$ | $\pm 11$ | - | V |
| Input Noise Voltage | $\mathrm{f}=1 \mathrm{kHz}, \mathrm{R}_{\mathrm{g}}=0 \Omega$ | 25 | - | 10 | - | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ |
| Input Noise Current | $\mathrm{f}=1 \mathrm{kHz}, \mathrm{R}_{\mathrm{g}}=0 \Omega$ | 25 | - | 4 | - | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ |
| TRANSFER CHARACTERISTICS |  |  |  |  |  |  |
| Large Signal Voltage Gain | $\mathrm{V}_{\mathrm{O}}= \pm 10 \mathrm{~V}$ | 25 | 10 | 16 | - | kV/V |
|  |  | Full | 5 | - | - | kV/V |
| Common Mode Rejection Ratio | $\mathrm{V}_{\mathrm{CM}}= \pm 10 \mathrm{~V}$ | Full | 70 | 90 | - | dB |
| Minimum Stable Gain |  | 25 | 1 | - | - | V/V |
| Unity Gain Bandwidth | $\mathrm{V}_{\mathrm{O}}=90 \mathrm{mV}$ | 25 | - | 40 | - | MHz |
| OUTPUT CHARACTERISTICS |  |  |  |  |  |  |
| Output Voltage Swing | $R_{L}=1 \mathrm{k} \Omega$ | Full | $\pm 10$ | $\pm 11$ | - | V |
| Output Current | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$ | 25 | $\pm 10$ | $\pm 15$ | - | mA |
| Output Resistance |  | 25 | - | 2 | - | $\Omega$ |
| Full Power Bandwidth (Note 3) | $\mathrm{V}_{\mathrm{P}}=10 \mathrm{~V}$ | 25 | 3 | 4 | - | MHz |
| Differential Gain | Note 4 | 25 | - | 0.1 | - | \% |
| Differential Phase | Note 4 | 25 | - | 0.2 | - | Degrees |
| Harmonic Distortion | Note 6 | 25 | - | <0.01 | - | \% |

Electrical Specifications $V_{S U P P L Y}= \pm 15 \mathrm{~V}, R_{L}=1 \mathrm{k} \Omega, C_{L} \leq 10 p F$, Unless Otherwise Specified (Continued)

| PARAMETER | TEST CONDITIONS | TEMP $\left({ }^{\circ} \mathrm{C}\right)$ | $\begin{gathered} \text { HA-2541-5 } \\ 0^{\circ} \mathrm{C} \text { TO } 75^{\circ} \mathrm{C} \end{gathered}$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX |  |
| TRANSIENT RESPONSE (Note 5) |  |  |  |  |  |  |
| Rise Time |  | 25 | - | 4 | - | ns |
| Overshoot |  | 25 | - | 40 | - | \% |
| Slew Rate |  | 25 | 200 | 250 | - | $\mathrm{V} / \mu \mathrm{s}$ |
| Settling Time | 10V Step To 0.1\% | 25 | - | 90 | - | ns |
|  | 10V Step To 0.01\% | 25 | - | 175 | - | ns |
| POWER REQUIREMENTS |  |  |  |  |  |  |
| Supply Current |  | 25 | - | 29 | - | mA |
|  |  | Full | - | - | 40 | mA |
| Power Supply Rejection Ratio | $\mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$ | Full | 70 | 78 | - | dB |

NOTES:
3. Full Power Bandwidth guaranteed based on slew rate measurement using: FPBW $=\frac{\text { Slew Rate }}{2 \pi V_{\text {PEAK }}}$.
4. Differential Gain and Phase are measured with a 1 V differential voltage at 5 MHz .
5. Refer to Test Circuits section of this data sheet.
6. $f=10 k H z ; A_{V}=5 ; V_{O}=14 V_{P-P}$.

## Test Circuits and Waveforms



NOTES:
7. $\mathrm{V}_{\mathrm{S}}= \pm 15 \mathrm{~V}$.
8. $A_{V}=+1$.
9. $C_{L} \leq 10 \mathrm{pF}$.

10. $A_{V}=-1$.
11. Feedback and summing resistor ratios should be $0.1 \%$ matched.
12. HP5082-2810 clipping diodes recommended
13. Tektronix P6201 FET probe used at settling point.

FIGURE 2. SETTLING TIME TEST CIRCUIT


Vertical Scale: $\mathrm{V}_{\mathrm{IN}}=100 \mathrm{mV} /$ Div., $\mathrm{V}_{\text {OUT }}=50 \mathrm{mV} /$ Div. Horizontal Scale: $20 \mathrm{~ns} /$ Div.

Vertical Scale: 5V/Div
Horizontal Scale: 50ns/Div.
LARGE SIGNAL RESPONSE

Test Circuits and Waveforms (Continued)


NOTES:
14. $\mathrm{V}_{\mathrm{S}}= \pm 15 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$.
15. $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.
16. Propagation delay variance is negligible over full temperature range.

Vertical Scale: $100 \mathrm{mV} /$ Div.
Horizontal Scale: 5ns/Div.

PROPAGATION DELAY

## Schematic Diagram



## Typical Applications (Also see Application Note AN550)

## Application 1

High power amplifiers and buffers are in use in a wide variety of applications. Many times the "high power" capability is needed to drive large capacitive loads as well as low value resistive loads. In both cases the final driver stage is usually a power transistor of some type, but because of their inherently low gain, several stages of pre-drivers are often required. The HA-2541, with its 10 mA output rating, is powerful enough to drive a power transistor without additional stages of current amplification. This capability is well demonstrated with the high power buffer circuit in Figure 3.
The HA-2541 acts as the pre-driver to the output power transistor. Together, they form a unity gain buffer with the ability to drive three $50 \Omega$ coaxial cables in parallel, each with a capacitance of 2000 pF . The total combined load is $16.6 \Omega$ and 6000 pF capacitance.


FIGURE 3. DRIVING POWER TRANSISTORS TO GAIN ADDITIONAL CURRENT BOOSTING

## Application 2

## VIDEO

One of the primary uses of the HA-2541 is in the area of video applications. These applications include signal construction, synchronization addition and removal, as well as signal modification. A wide bandwidth device such as the HA-2541 is well suited for use in this class of amplifier. This, however, is a more involved group of applications than ordinary amplifier applications since video signals contain precise DC levels which must be retained.

The addition of a clamping circuit restores DC levels at the output of an amplifier stage. The circuit shown in Figure 4 utilizes the HA-5320 sample and hold amplifier as the DC clamp. Also shown is a 3.57 MHz trap in series, which will block the color burst portion of the video signal and allow the DC level to be amplified and restored.


FIGURE 4. VIDEO DC RESTORER

NOTE: Tested Offset Adjustment Range is $\mid \mathrm{V}_{\mathrm{OS}}+$ 1 mV | minimum referred to output. Typical range is $\pm 15 \mathrm{mV}$ for $\mathrm{R}_{\mathrm{T}}=5 \mathrm{k} \Omega$.

## Typical Performance Curves



FIGURE 5. INPUT RESISTANCE vs FREQUENCY


FIGURE 7. NOISE DENSITY vs FREQUENCY


FIGURE 9. OUTPUT VOLTAGE SWING vs SUPPLY VOLTAGE


FIGURE 6. OFFSET VOLTAGE vs TEMPERATURE (6 REPRESENTATIVE UNITS)


FIGURE 8. BIAS CURRENT vs TEMPERATURE (6 REPRESENTATIVE UNITS)


FIGURE 10. OUTPUT CURRENT vs SUPPLY VOLTAGE

Typical Performance Curves (Continued)


FIGURE 11. SUPPLY CURRENT vs SUPPLY VOLTAGE


FIGURE 13. PSRR vs SUPPLY VOLTAGE (AVERAGE OF 3 LOTS)


FIGURE 15. REJECTION RATIOS vs FREQUENCY


FIGURE 12. SLEW RATE vs SUPPLY VOLTAGE (NORMALIZED WITH V ${ }_{S}= \pm 15 \mathrm{~V}$ AT $25^{\circ} \mathrm{C}$ )


FIGURE 14. CMRR vs SUPPLY VOLTAGE (AVERAGE OF 3 LOTS)


FIGURE 16. OPEN LOOP GAIN vs SUPPLY VOLTAGE (AVERAGE OF 3 LOTS)

## Typical Performance Curves (Continued)



FIGURE 17. GAIN AND PHASE FREQUENCY RESPONSE

$\mathbf{R}_{\mathbf{S}}=0 \Omega \quad \mathbf{R}_{\mathbf{S}}=\mathbf{5 k} \Omega$
$\mathrm{R}_{\mathrm{S}}=50 \mathrm{k} \Omega$ зым
FIGURE 18. SMALL SIGNAL BANDWIDTH vs SOURCE RESISTANCE


FIGURE 19. CLOSED LOOP FREQUENCY RESPONSE

## Die Characteristics

DIE DIMENSIONS:
80 mils $\times 90$ mils $\times 19$ mils
$2020 \mu \mathrm{~m} \times 2280 \mu \mathrm{~m} \times 483 \mu \mathrm{~m}$
METALLIZATION:
Type: AI, 1\% Cu
Thickness: $16 \mathrm{k} \AA \pm 2 k \AA$

## PASSIVATION:

Silox Thickness: $12 \mathrm{k} \AA+2 \mathrm{~K} \AA$
Nitride Thickness: $3.5 \mathrm{k} \AA \pm 1.5 \mathrm{k} \AA$

## Metallization Mask Layout

## SUBSTRATE POTENTIAL (Powered Up):

## V-

## TRANSISTOR COUNT:

## 41

## PROCESS:

Bipolar Dielectric Isolation


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